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$1 = r \text{e}^{ax} \cos (y) + bx + c$ where we have used the formula $\cos A \cos B - \sin A \sin B = \cos (A + B)$ Differentiating again and simplifying as before, $y. 2 = r2e^{ax} \cos (y) - r \text{e}^{ax} \sin (y) + b$. Similarly $y. 3 = r3e^{ax} \cos (y) - r \text{e}^{ax} \sin (y) + b$ Thus $y \text{r} \text{e}^{ax} \cos (y) + bx + c = \frac{1}{a^2 + b^2} (a^2 y + b^2 x) + \frac{1}{a^2 + b^2} (a^2 \cos (y) - b \sin (y)) + c$. Where $r = \frac{1}{a^2 + b^2}$ and $\phi = \tan^{-1}(b/a)$.

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It is important to note that $[T(x)]_{B_2} = T[B_1, B_2] [x]_{B_1}$. That is, we multiply the matrix of the linear transformation with the coordinates $[x]_{B_1}$, of the vector $x \in V$ to obtain the coordinates of the vector $T(x)$

W. 3. If A is an $m \times n$ matrix, then A induces a linear transformation $T_A: \mathbb{R}^n \rightarrow \mathbb{R}^m$, defined by $T_A(x) = Ax$.

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